First, the module Scope:

1. As square wave signal generator which generates a square wave signal for experimental development use.

2. used to generate drive stepper motor drives a square wave signal.

3. produce adjustable pulse for MCU to use.

4. Have an adjustable pulse control-related circuits.

Second, a brief description:

1. Size: 3.1CM * 2.2CM

1, the main chip: NE555;

2, the input voltage: 5V-15VDC. 5V supply, the output current can be around 15MA; when 12V power supply, output current is about 35MA;

3, the input current: \geq 100MA

4, the output amplitude:. 4.2V V-PP to 11.4V V-PP (different depending on the input voltage, the output amplitude will be different)

5, the maximum output current: \geq 15MA (5V supply, V-PP is greater than 50%), \geq 35MA (12V power supply, V-PP is greater than 50%)

Three Advantages:

1, the output with LED indication, there is no straightforward output (low level LED volume, high LED off frequency is relatively low LED flashing);

2, the output frequency range of grades available, the output frequency is more continuously adjustable;

Low-profile: $1Hz \sim 50Hz$

IF file: 50Hz \sim 1kHz

High-frequency gear: 1KHz ~ 10kHz

High Frequency file: 10kHz ~ 200kHz

3, you can fine-tune the output duty cycle, duty cycle and frequency than separately adjustable duty cycle will change the frequency modulation;

4, the output frequency is adjustable;

Cycle T = 0.7 (RA + 2RB) C

RA, RB is adjustable 0-10K;

When the low-profile C = 0.001UF;

When IF shift C = 0.1UF;

High-frequency gear C = 1UF;

When high-frequency gear C = 100UF, therefore frequency waveform buyers can own calculations.